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Summary

- During Hurricanes Harvey and Irma we used AMSR2 (passive microwave) remote sensing data to map flood extents in near real time
- Results begin with the first post-storm rain-free satellite passes and track flood evolution over time
- Our standard flood extent algorithm derives flooded fraction from normalized 22-km AMSR2 or GMI data and downscals it to a ~90-m flood map using a relative floodability database built from topography, hydrology, and Global Surface Water Occurrence (Pekel et al., 2016) data
- Here we tested experimental algorithm versions designed to rapidly map the maximum flood extent and provide updates at least daily
- Versions of the maps shown here were shared in real time during the floods through, e.g., the Global Flood Partnership

Standard flood extent depiction SFED

- Enforces consistency between historical and near-real-time products
- Minimizes false positive rates
- Uses 3-day averaging to improve precision for large, longer-duration floods
- Used in, e.g., insurance applications with index-based payout triggers

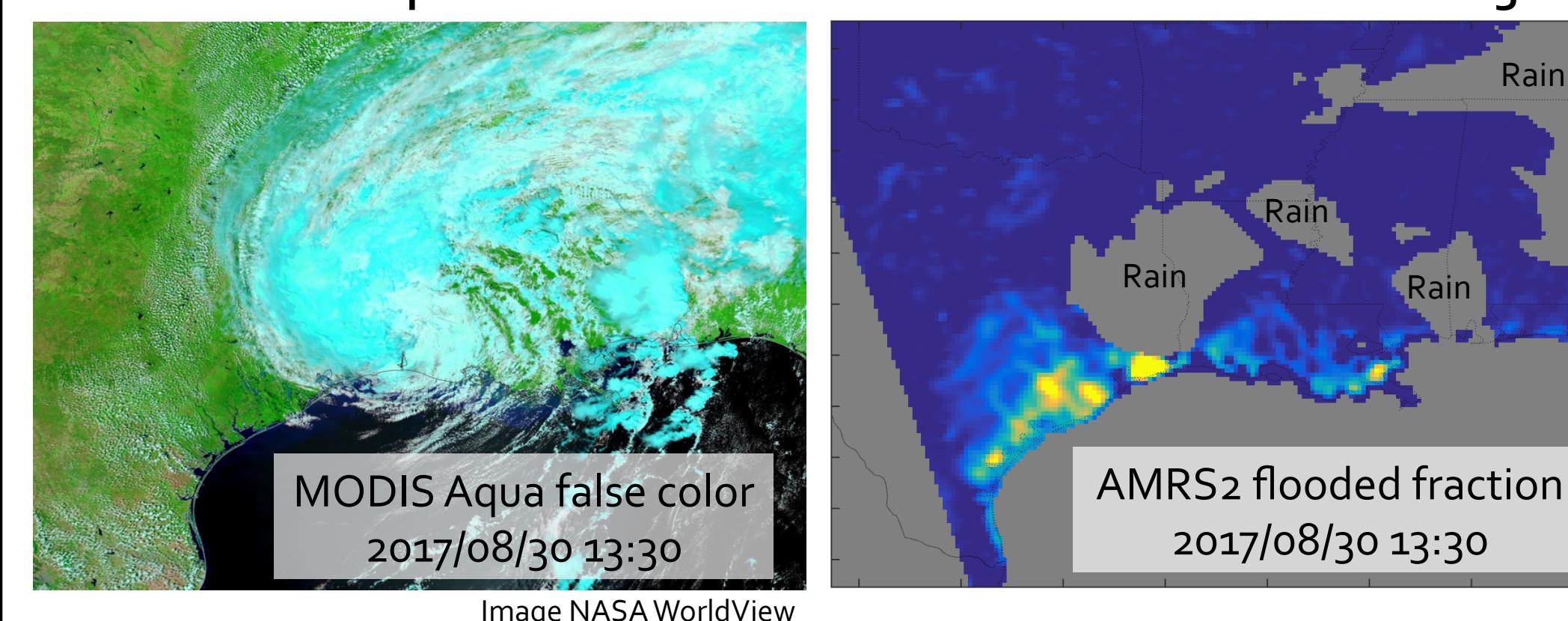
Rapid-response flood extent depiction RFED

- Ignores false-positive flags; to be used only as a flood event unfolds
- Uses 3-day maximum flooded fraction to capture full extent of floods
- Intended to help decision-makers monitor and respond to on-going floods

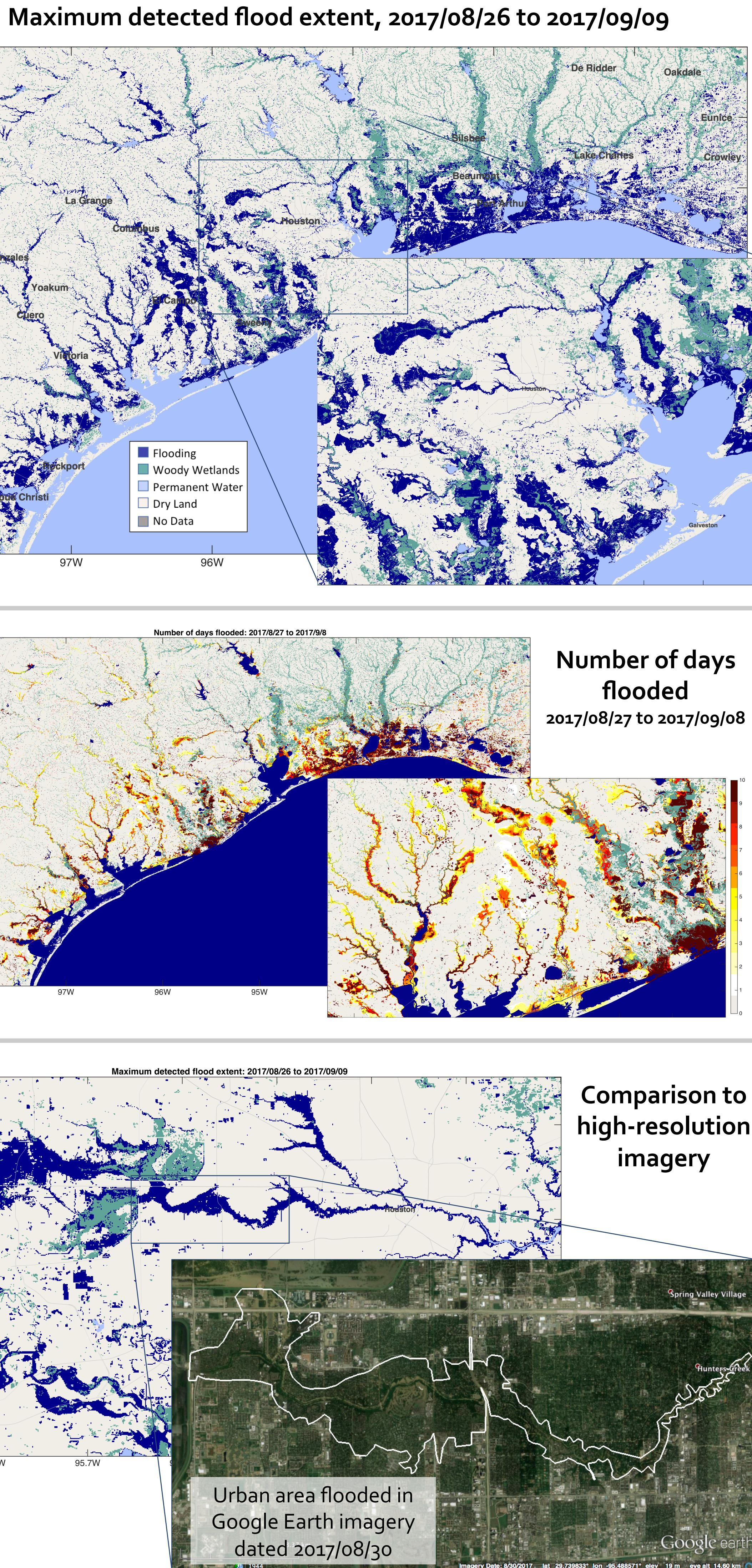
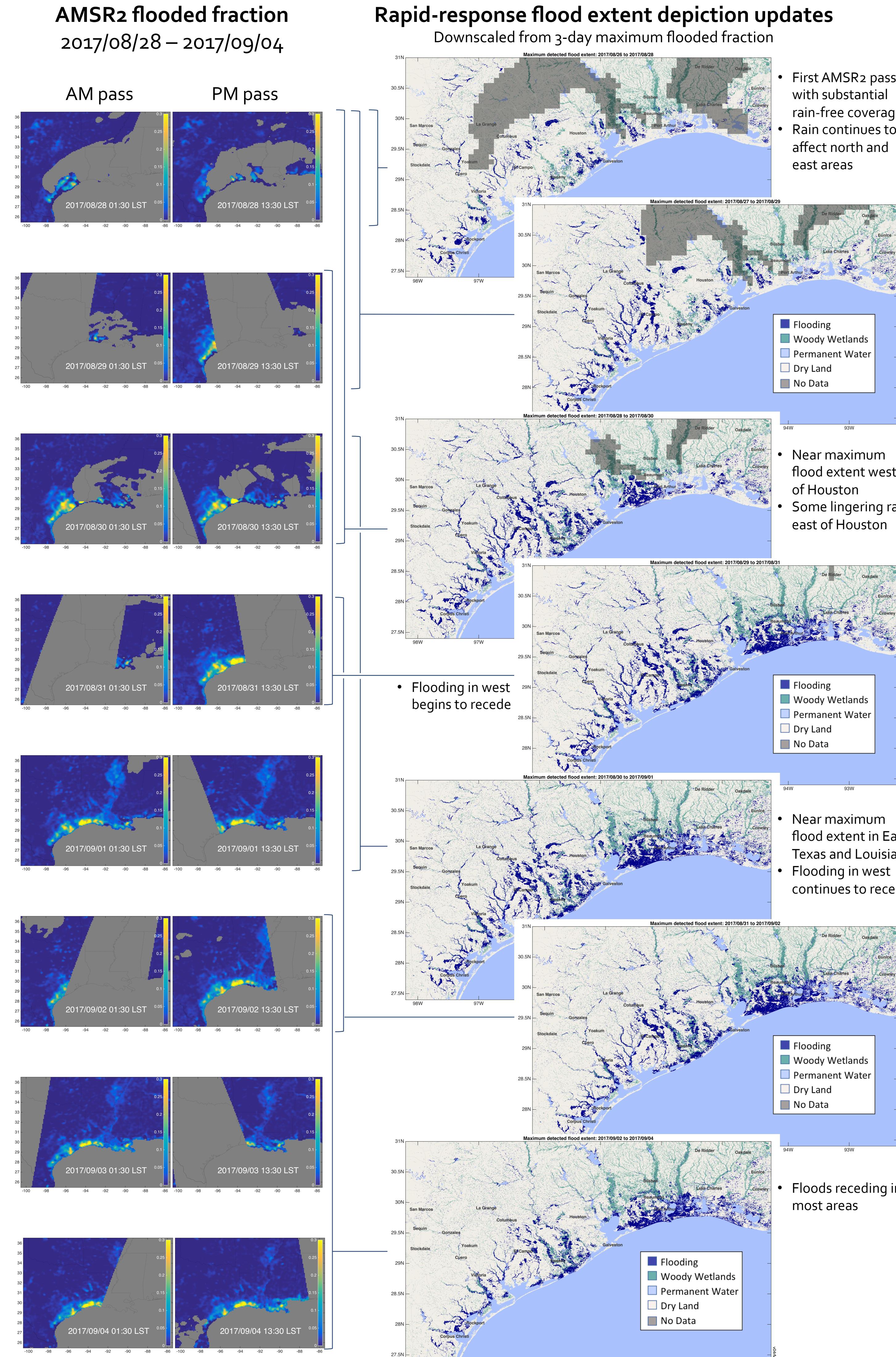
Why use microwave sensors to map floods?

- They can provide twice-daily measurements globally
 - They "see through" non-precipitating clouds
 - They make measurements day and night
- They provide a historical record from 1992 to the present from multiple satellite sensors
 - SSM/I, TMI, AMSR-E, AMSR2, GMI
- Multiple satellite sensors currently provide redundant data for more reliable near-real-time operations
 - AMSR2, GMI, [WSF-M launch ~2022]
- Our algorithms address key microwave sensor limitations
 - Coarse resolution:** Downscaling algorithm depicts floods at finer scale using relative floodability database
 - Ambiguity:** Temporal-spatial processing filters out non-flood signals

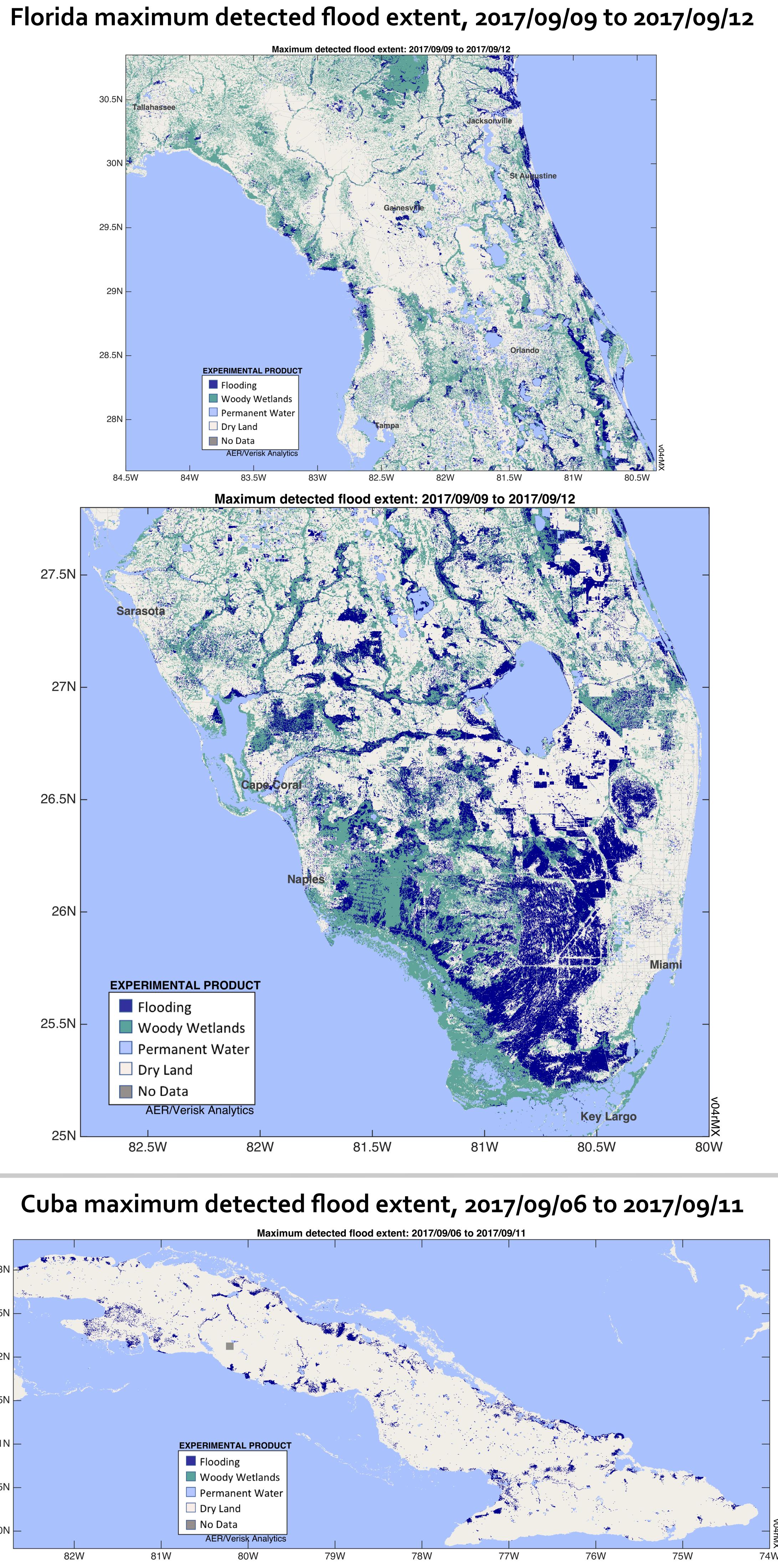
Clouds block optical sensors microwave sensors see through



Harvey Daily Flood Evolution and Maximum Extent



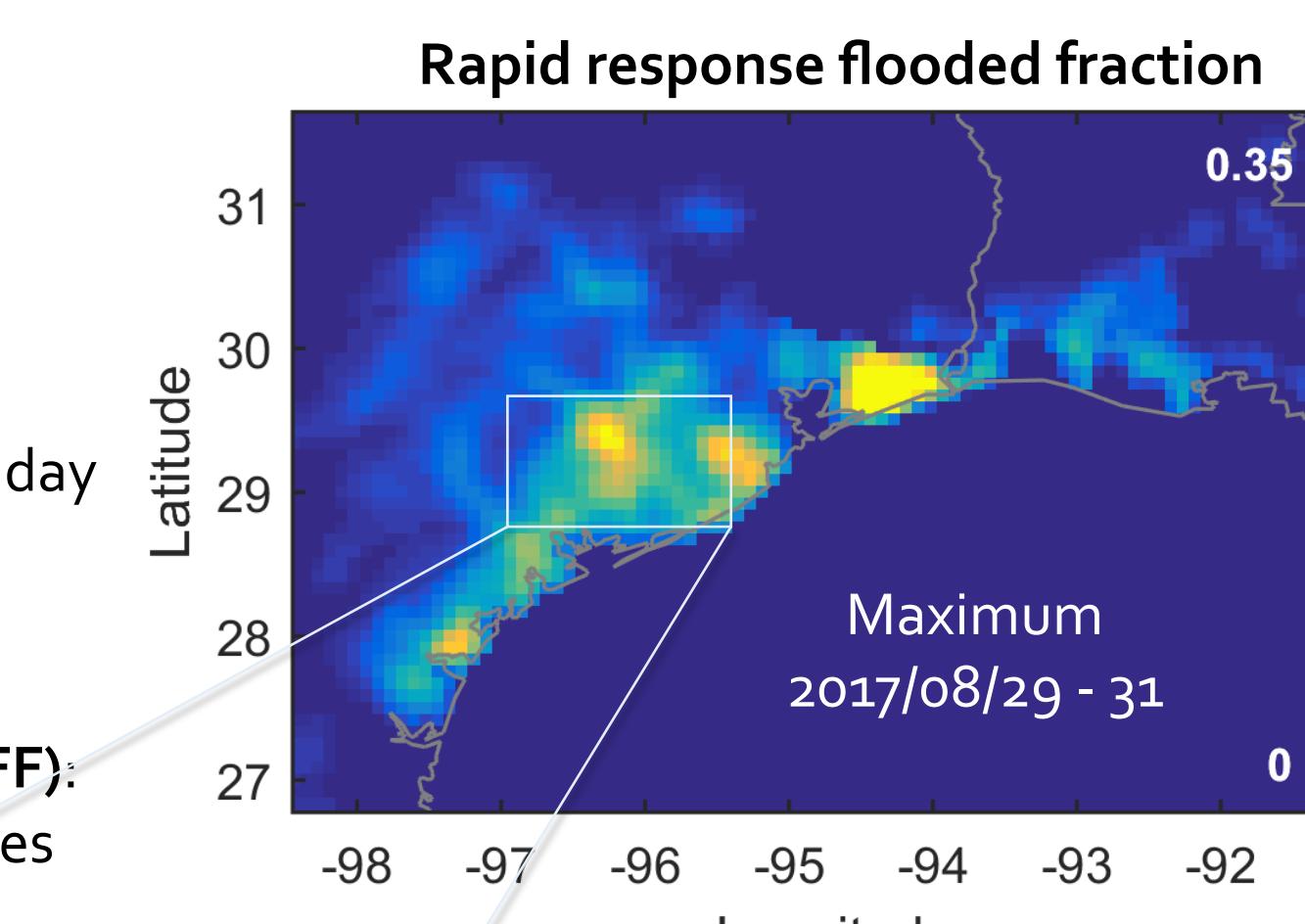
Irma Maximum Flood Extent



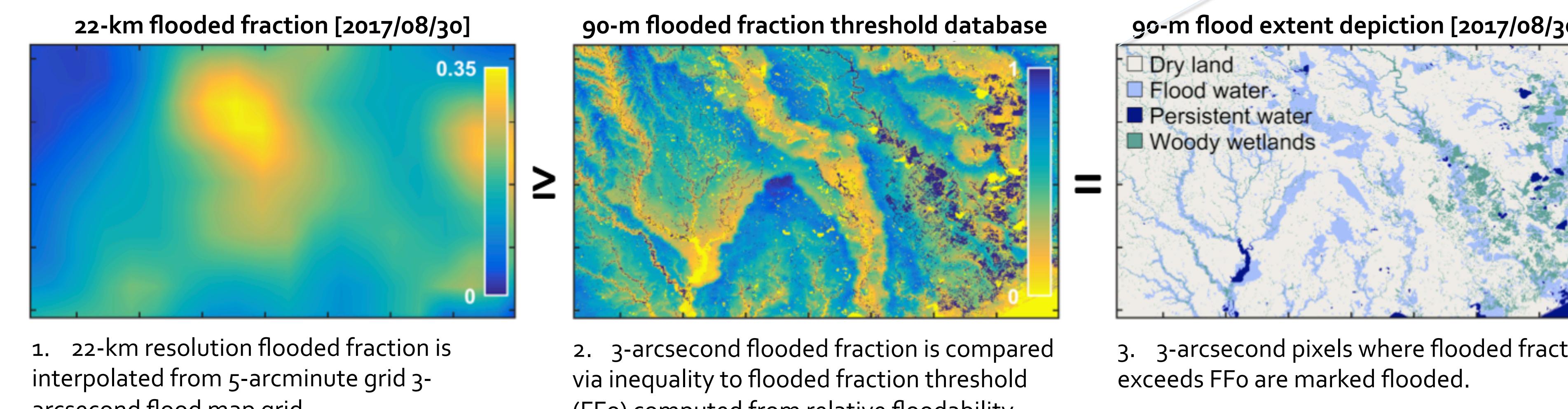
Flood Mapping Methodology

Flooded fraction from microwave data

- Footprint matching and regridding: isolates temporal variation at grid locations on a 22-km circularized footprint scale
- Rain flagging: liberal flagging reduces flood detection false negatives
- Linearization: "Q" transform linearizes polarization ratio index vs. water fraction
- Atmospheric correction: enhances land/water contrast
- Flooded fraction (initial): end-member mixing model makes a best estimate of the dry-land end-member, O_{dr} per each gridded footprint location
- False positive "flash" detection: temporal/spatial filter flags large areas of sudden flooding as likely false positives
- Compute daily flooded fraction (FF)
 - Combines initial flooded fraction data over 3-day period, day and night observations, excluding flagged data
 - Standard: 3-day weighted mean
 - Rapid response: 3-day maximum
- Apply minimum detectable flooded fraction limit (FF>MDFF): reduces false positives at the expense of smaller flood features



Downscaling flooded fraction



FloodScan Web Interface with Flooded Fraction Time Series Analysis

FloodScan provides web access to historical and near-real-time flood maps from AER's standard flood mapping system.

- Daily historical 90-m flood maps
- Automatic daily updates
- Continent-wide coverage
 - North America: 2002-present
 - South America: 2002-present
 - Africa: 1992-present
- Plots historical flooded fraction time series at any location to instantly put flooding into historical context

floodscan.aer.com

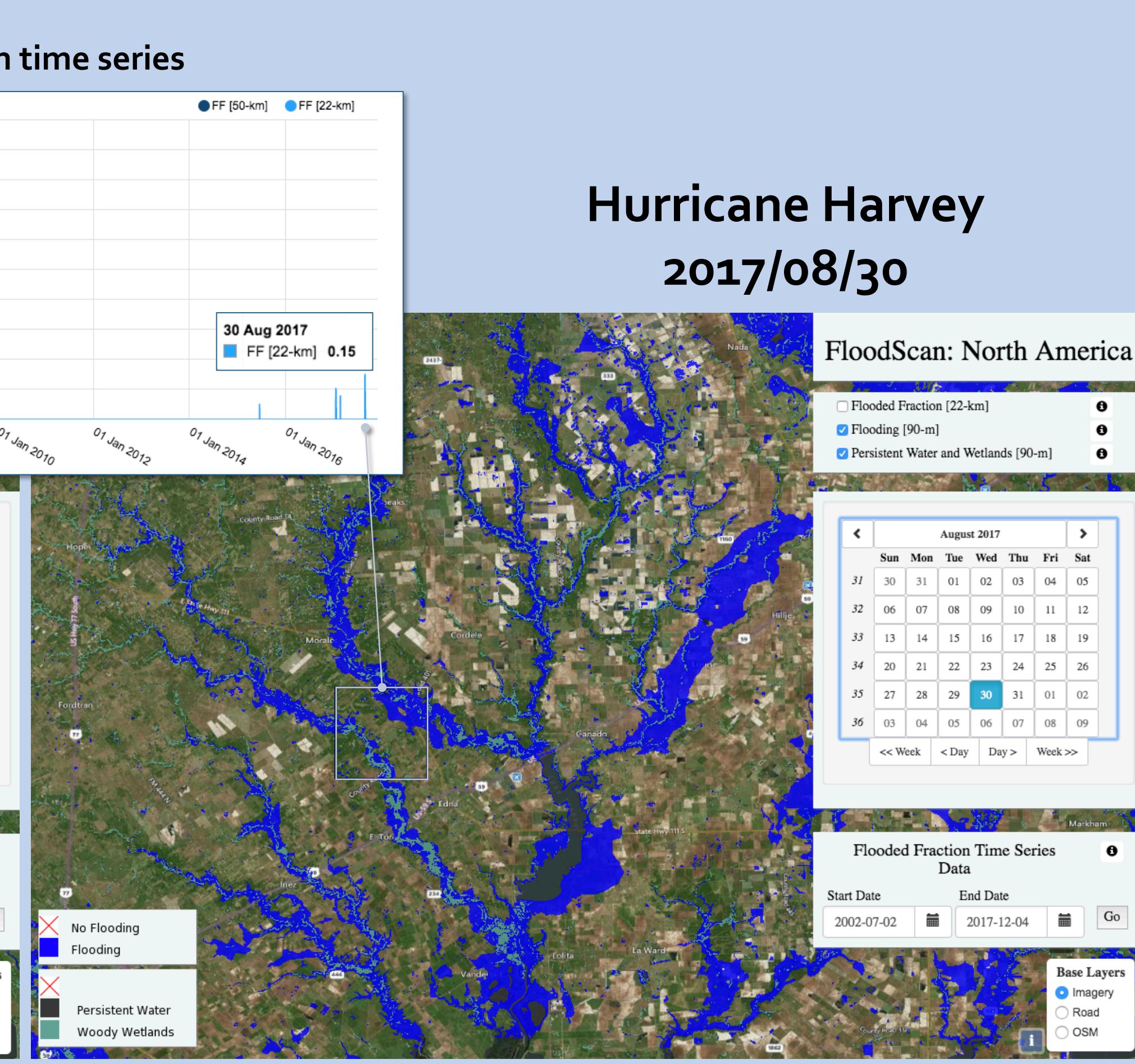
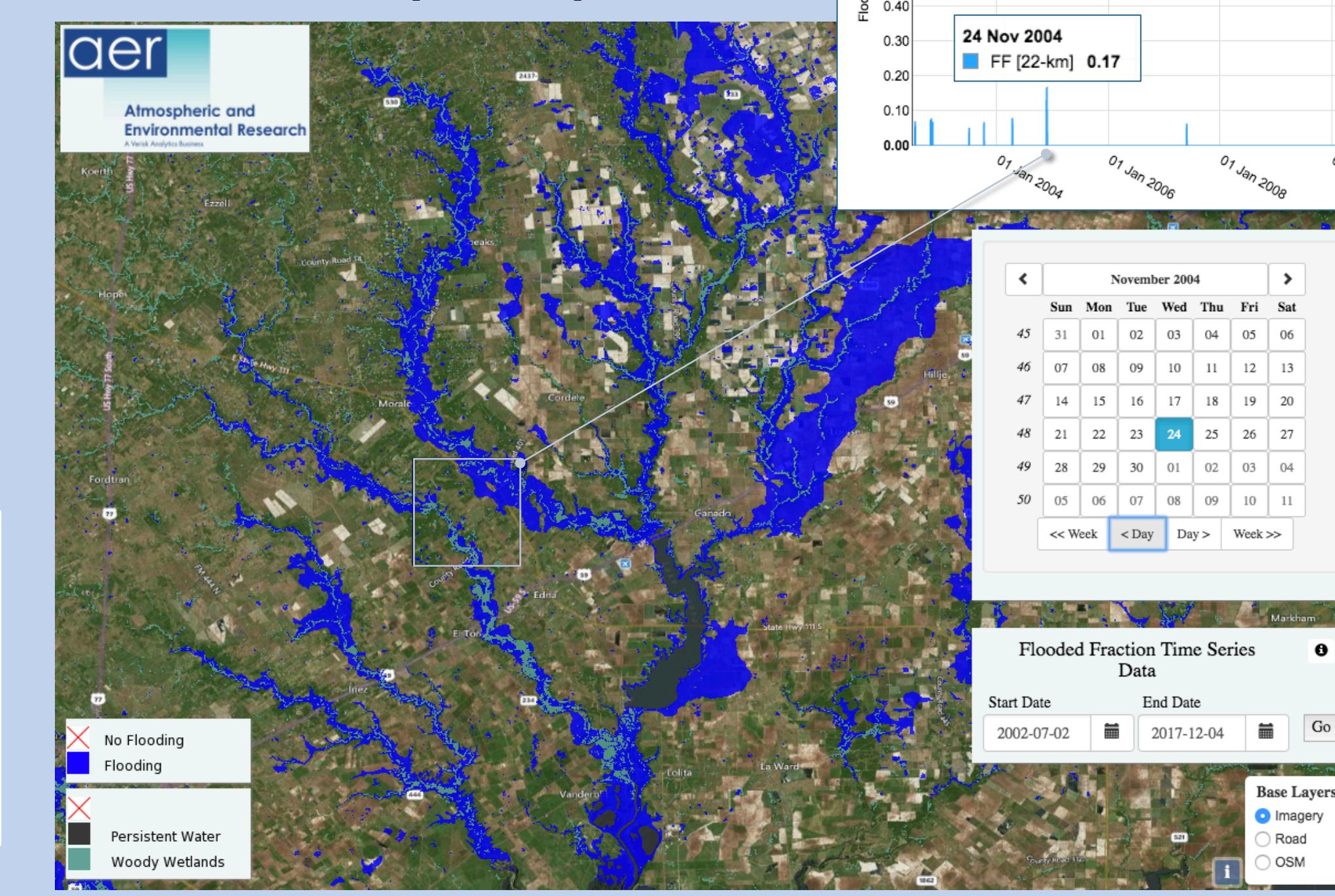
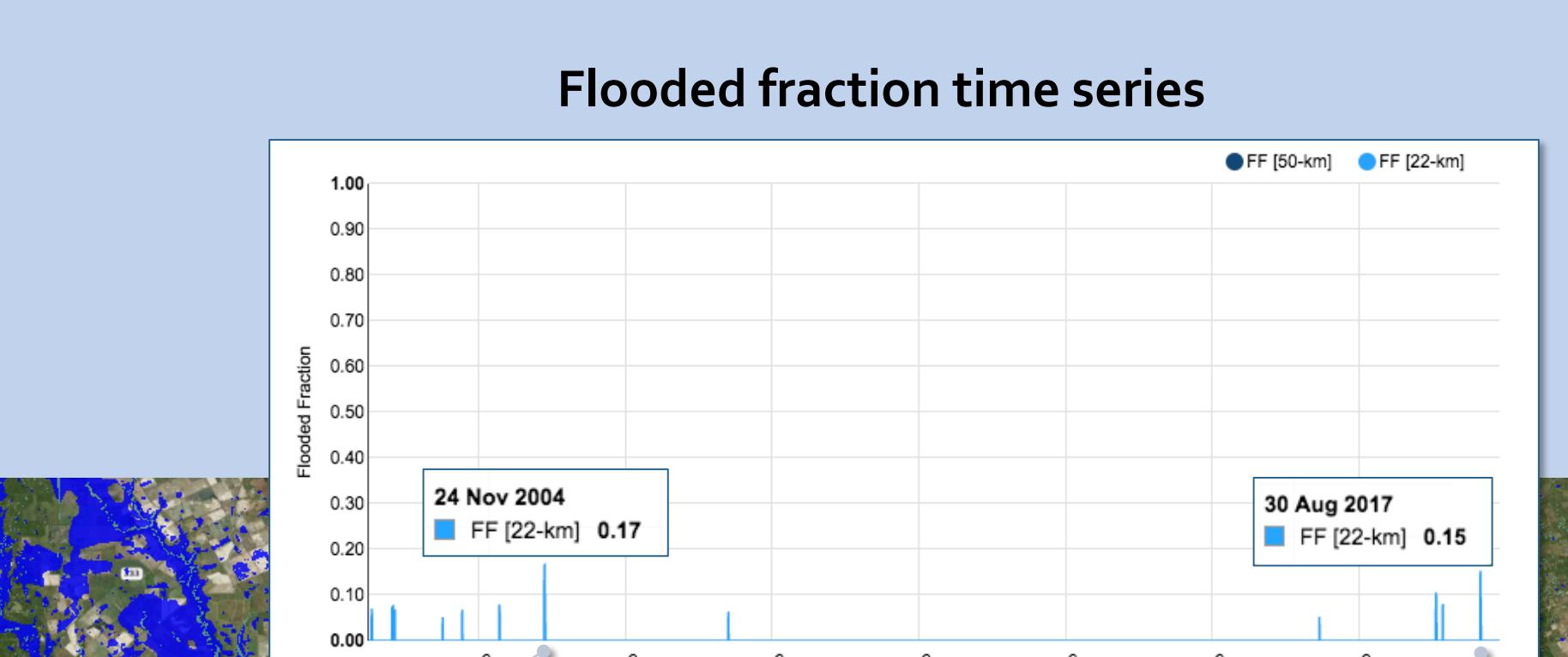


References

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Jean-François Pekel, Andrew Cottam, Neil Gorelick, Alan S. Belward, Nature 540, 418-422 (2016). (doi:10.1038/nature20584)



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